
ROOT: a HEP tool for data analysis

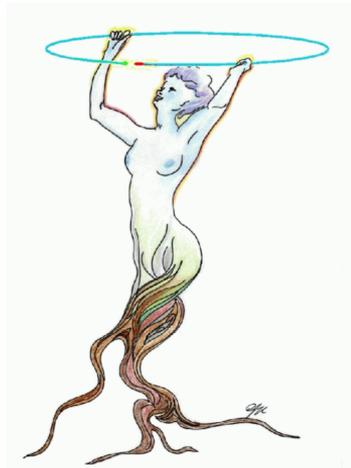
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ROOT is...

- **A scientific software toolkit for data analysis**
 - User code (\Rightarrow macros) is C++ using ROOT classes (\Rightarrow T***).
 - TFile \Rightarrow basic I/O
 - TH1F \Rightarrow 1D-histogram with floating-point precision
 - TF1 \Rightarrow a generic real-valued 1D-function
 - ...
 - Macros can be either interpreted on-the-fly or compiled & executed
 - ROOT classes/functions can be used via automatic Python bindings (\Rightarrow PyROOT)

```
import ROOT
f = ROOT.TFile.Open(...)
h = ROOT.TH1F()
```
- **Project developed & maintained by CERN** (currently at ROOT 6.X)
 - Online manual, tutorials, forum: <https://root.cern.ch/>
 - Open-source: can either compile the source code, or use binaries



I/O & operations in ROOT

● Input/output

- Data stored in binary files (⇒ **.root**). Many compressions possible (ZLIB, LZMA, LZ4, ZSTD)
- Can save graphic objects into most used formats: .eps, .png, .pdf, .jpeg, **.C** (⇒ C++ code)

● Operations

- Commands issued into the **ROOT prompt**:

```
> root
```

```
root [0] TFile* f = TFile::Open("my_file.root")
```

- Code interpreted on-the-fly (⇒ **Cling**):

```
> root
```

```
root[0] .L my_macro.C // func() is defined here
```

```
root[1] func()
```

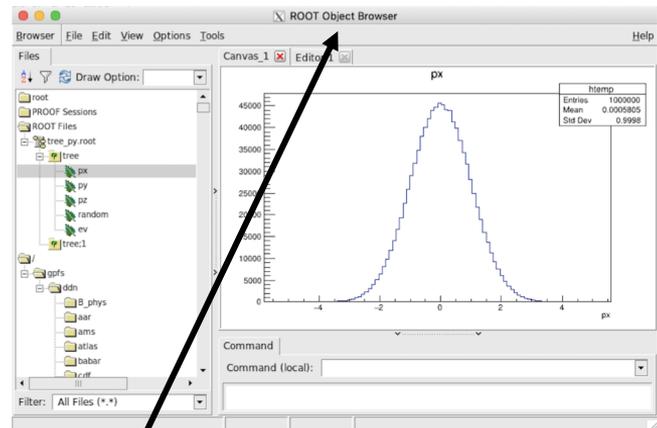
```
root[2] .x snippet.C // C++ code within '{ }' brackets
```

- Code compiled, linked, and executed (⇒ **ACLiC**)

```
> root
```

```
root[0] .L my_macro.C++ // generates my_macro_C.so
```

```
root[1] func()
```



ROOT comes with its own **GUI** (⇒ **TBrowser**) for browsing file content and prompt plotting

Interesting features (from a HEP perspective)

- **Efficient I/O of N-dimensional data of arbitrary type (⇒ TTree)**
 - Can store objects, arrays, and pointers of basic types, C structures, C++ classes

```
root[0] tree->Scan()
```

```
*****  
*      Row *      Var0      *      Var1      *      Var2      *      Var4      *  
*****  
*      0      *      0.2832548      *      1.0946351      *      1.2784594      *      0      *  
*      1      *      1.2402626      *      -0.285862      *      1.6199687      *      1      *  
*****
```

COLUMNS ⇒ variables

ROWS ⇒ events

- **Native mathematical environment (⇒ ROOT::Math::)**
- **Linear algebra (⇒ TLorentzVector, TMatrixD, TDecomp[SVD,LU,QRH...])**
- **N-dimensional minimization and integration (⇒ Minuit, GSL)**
- **Monte Carlo studies (random number generation)**
- **MVA's (aANN, BDT, kNN, likelihood, ...) for regression/classification (⇒ TMVA)**
- **Unfolding (⇒ TUnfold)**

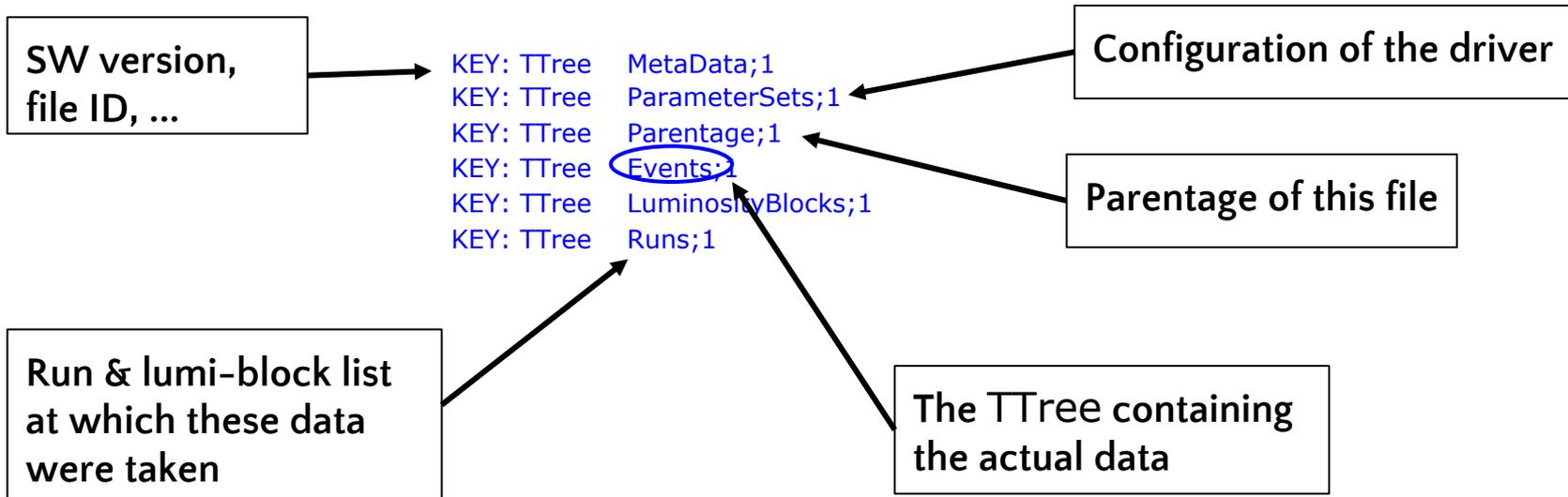
A concrete example: ROOT-based data for CMS

CMS data stored into ROOT files with different content (**data tiers**)

(detector...) RAW \Rightarrow RECO \Rightarrow AOD \Rightarrow MiniAOD \Rightarrow NanoAOD (... analysis)

- Look e.g. at a MiniAOD Monte Carlo file (-50 kB/event):

34705FB5-CE8C-E911-B0E4-00144F45BD0E.root (1 runs, 14 lumis, 13258 events, 565781558 bytes)



A concrete example: ROOT-based data for CMS

Looking at the Event TTree:

	Type	Module	Label	Process
User-defined classes	GenEventInfoProduct	"generator"	""	"SIM"
	LHEEventProduct	"externalLHEProducer"	""	"SIM"
	edm::TriggerResults	"TriggerResults"	""	"SIM"
	vector<reco::GenMET>	"genMetTrue"	""	"SIM"
	vector<reco::GenMET>	"genMetTrue"	""	"HLT"
	vector<pat::Electron>	"slimmedElectrons"	""	"PAT"
STL containers of user-defined classes	vector<pat::IsolatedTrack>	"isolatedTracks"	""	"PAT"
	vector<pat::Jet>	"slimmedJets"	""	"PAT"
	vector<pat::Jet>	"slimmedJetsAK8"	""	"PAT"
	vector<pat::Jet>	"slimmedJetsPuppi"	""	"PAT"
	vector<pat::MET>	"slimmedMETs"	""	"PAT"
	vector<pat::Muon>	"slimmedMuons"	""	"PAT"
	vector<pat::Photon>	"slimmedPhotons"	""	"PAT"
	vector<reco::GenJet>	"slimmedGenJets"	""	"PAT"
STL containers of STL classes	vector<string>	"slimmedPatTrigger"	""	"PAT"
	unsigned int	"bunchSpacingProducer"	""	"PAT"
	double	"fixedGridRhoAll"	""	"RECO"

Setup the environment

All the material can be also found here:
https://github.com/bianchini/SNS_DAS

1. Open a terminal

2. Create a working directory

```
> mkdir ROOT_Tutorial
```

```
> cd ROOT_Tutorial/
```

1. Download the material

```
> wget https://github.com/bianchini/SNS\_DAS/archive/master.zip
```

```
> unzip master.zip; cd SNS_DAS-master/
```

For this tutorial, ROOT is made available inside a singularity container.

- To open ROOT:

```
> singularity exec /opt/cern_root/cern_root.sif root -l
```

- To execute Python macros that import the ROOT module:

```
> singularity exec /opt/cern_root/cern_root.sif python -c "import ROOT"
```

FOR TODAY, REMEMBER TO PUT **singularity exec /opt/cern_root/cern_root.sif**
BEFORE ANY CALL TO ROOT/Python IN THE TERMINAL

Basic ROOT commands

- Open ROOT
 - > root -l // don't display initial ROOT logo
 - > root -b // batch mode (N.B. no graphic windows can be opened)
- List content of the ROOT current directory
 - root[0] .ls // objects in memory will be displayed
- Exit ROOT
 - root[0] .q
- The ROOT prompt provides auto-completion (TAB), forward-backward search (↑,↓) and regex search in the history (CTRL-R)

Exercise 1: create a dataset (\Rightarrow tree.C)

```
#include "TFile.h"
#include "TTree.h"
#include "TH2.h"
#include "TRandom.h"

void make_tree(Int_t nevents=100000)
{
    TFile* file = new TFile("tree_C.root","RECREATE", "");
    TTree* tree = new TTree("tree","A simple Tree");

    Float_t px, py, pz;
    Double_t random;
    Int_t ev;

    tree->Branch("px",&px,"px/F");
    tree->Branch("py",&py,"py/F");
    tree->Branch("pz",&pz,"pz/F");
    tree->Branch("random",&random,"random/D");
    tree->Branch("ev",&ev,"ev/I");
```

```
    for (Int_t i = 0 ; i<nevents ; i++) {
        gRandom->Rannor(px,py);
        pz = px*px + py*py;
        random = gRandom->Rndm();
        ev = i;
        tree->Fill();
    }

    tree->Write();
}
```

Exercise 1: create a dataset (\Rightarrow tree.C)

```
#include "TFile.h"  
#include "TTree.h"  
#include "TH2.h"  
#include "TRandom.h"
```

No need to set full path. ROOT has its own collection of predefined include paths (\Rightarrow `root[0].include`)

```
void make_tree(Int_t nevents=100000)  
{
```

```
  TFile* file = new TFile("tree_C.root","RECREATE", "");  
  TTree* tree = new TTree("tree","A simple Tree");
```

```
  Float_t px, py, pz;  
  Double_t random;  
  Int_t ev;
```

```
  tree->Branch("px",&px,"px/F");  
  tree->Branch("py",&py,"py/F");  
  tree->Branch("pz",&pz,"pz/F");  
  tree->Branch("random",&random,"random/D");  
  tree->Branch("ev",&ev,"ev/I");
```

```
  for (Int_t i = 0 ; i<nevents ; i++) {  
    gRandom->Rannor(px,py);  
    pz = px*px + py*py;  
    random = gRandom->Rndm();  
    ev = i;  
    tree->Fill();  
  }  
  
  tree->Write();  
}
```

Exercise 1: create a dataset (\Rightarrow tree.C)

```
#include "TFile.h"
#include "TTree.h"
#include "TH2.h"
#include "TRandom.h"
```

```
void make_tree(Int_t nevents=100000)
{
```

```
TFile* file = new TFile("tree_C.root","RECREATE", "");
TTree* tree = new TTree("tree","A simple Tree");
```

```
Float_t px, py, pz;
Double_t random;
Int_t ev;
```

```
tree->Branch("px",&px,"px/F");
tree->Branch("py",&py,"py/F");
tree->Branch("pz",&pz,"pz/F");
tree->Branch("random",&random,"random/D");
tree->Branch("ev",&ev,"ev/I");
```

A classical C++ function.

N.B. ROOT defines new types for int, float, ...

E.g.: int \rightarrow **Int_t**

```
for (Int_t i = 0 ; i<nevents ; i++) {
    gRandom->Rannor(px,py);
    pz = px*px + py*py;
    random = gRandom->Rndm();
    ev = i;
    tree->Fill();
}

tree->Write();
}
```

No need to call explicit destructors here.

\Rightarrow after execution, objects remains "alive"
(will be destroyed when ROOT is quitted)

Exercise 1: create a dataset (\Rightarrow tree.C)

```
#include "TFile.h"
#include "TTree.h"
#include "TH2.h"
#include "TRandom.h"
```

```
void make_tree(Int_t nevents=100000)
{
```

```
    TFile* file = new TFile("tree_C.root","RECREATE");
    TTree* tree = new TTree("tree","A simple Tree");
```

```
    Float_t px, py, pz;
    Double_t random;
    Int_t ev;
```

```
    tree->Branch("px",&px,"px/F");
    tree->Branch("py",&py,"py/F");
    tree->Branch("pz",&pz,"pz/F");
    tree->Branch("random",&random,"random/D");
    tree->Branch("ev",&ev,"ev/I");
```

ROOT file created from scratch (\Rightarrow "RECREATE")
A new **TTree** object is also created

```
    for (Int_t i = 0 ; i<nevents ; i++) {
        gRandom->Rannor(px,py);
        pz = px*px + py*py;
        random = gRandom->Rndm();
        ev = i;
        tree->Fill();
    }
```

```
    tree->Write();
}
```

Objects that we want to be persistently save (e.g. **tree**) will be written into the currently open writable file

Exercise 1: create a dataset (\Rightarrow tree.C)

```
#include "TFile.h"
#include "TTree.h"
#include "TH2.h"
#include "TRandom.h"
```

Auxiliary variables to
store intermediate values

```
void make_tree(Int_t nevents=100000)
{
```

```
TFile* file = new TFile("tree_C.root","RECREATE","");
TTree* tree = new TTree("tree","A simple Tree");
```

```
Float_t px, py, pz;
Double_t random;
Int_t ev;
```

```
tree->Branch("px",&px,"px/F");
tree->Branch("py",&py,"py/F");
tree->Branch("pz",&pz,"pz/F");
tree->Branch("random",&random,"random/D");
tree->Branch("ev",&ev,"ev/I");
```

Define the TBranches
(\Rightarrow columns) for this TTree

```
for (Int_t i = 0 ; i<nevents ; i++) {
  gRandom->Rannor(px,py);
  pz = px*px + py*py;
  random = gRandom->Rndm();
  ev = i;
  tree->Fill();
}

tree->Write();
}
```

Variable type is specified
here (e.g. "/F", "/I", "/D")

Exercise 1: create a dataset (\Rightarrow tree.C)

```
#include "TFile.h"
#include "TTree.h"
#include "TH2.h"
#include "TRandom.h"

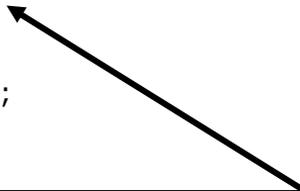
void make_tree(Int_t nevents=100000)
{
    TFile* file = new TFile("tree_C.root","RECREATE", "");
    TTree* tree = new TTree("tree","A simple Tree");

    Float_t px, py, pz;
    Double_t random;
    Int_t ev;

    tree->Branch("px",&px,"px/F");
    tree->Branch("py",&py,"py/F");
    tree->Branch("pz",&pz,"pz/F");
    tree->Branch("random",&random,"random/D");
    tree->Branch("ev",&ev,"ev/I");
}
```

```
for (Int_t i = 0 ; i<nevents ; i++) {
    gRandom->Rannor(px,py);
    pz = px*px + py*py;
    random = gRandom->Rndm();
    ev = i;
    tree->Fill();
}

tree->Write();
}
```



Start the “event” loop.
At each iterate i , the **Fill()** command fills one row of the TTree using current data found at the branch address

Inspecting a ROOT file (\Rightarrow tree_C.root)

- Let's run the macro tree.C

```
> root -l  
root[0] .L tree.C  
root[1] make_tree(100000)  
root[2] .q
```

Equivalent to:

```
> root -l -b -e 'gROOT->ProcessLine(".L tree.C"); gROOT->ProcessLine("make_tree(100000)";
```

We could also have compiled the code (\Rightarrow tree_C.so) and run it:

```
> root -l -b -e 'gROOT->ProcessLine(".L tree.C++"); gROOT->ProcessLine("make_tree(100000)";
```

- Let's inspect the file content (Q: what is the size of the output file?)

```
> root -l tree_C.root // equivalent to starting ROOT prompt and then opening the TFile  
root[0] .ls  
root[1] tree->Print()  
root[2] new TBrowser()
```

Inspecting a ROOT file (\Rightarrow tree_C.root)

- From the ROOT prompt, you can draw the content of any TBranch

```
root[0] tree->Draw("px")
```

```
root[1] tree->Draw("px", "py>0 && random<0.5") // 2nd argument is a 0/1 weight per-event
```

```
root[2] tree->Draw("px:py", "py>0 && random<0.5", "colz") // ":" means "one vs the other"
```

```
root[3] tree->Draw("px:py:pz", "py>0 && random<0.5", "lego")
```

- The output of Draw() can be also redirected into a named histogram:

```
root[4] tree->Draw("px>>h(100,-3,3)") // TH1F object "h" is created
```

```
root[5] h->GetMean()
```

- You can draw any function of the input branches:

```
root[6] tree->Draw("px*TMath::Sin(py)/TMath::Log(pz+1)")
```

When functions are too complicated to fit into a line:

- Write the function in a separate macro (\Rightarrow func.C)
- Load the function macro within ROOT (\Rightarrow root[1] .L func.C)
- Now, you can now use func(...) within Draw(). E.g.:

```
root[7] tree->Draw("px*TMath::Sin(py)/TMath::Log(pz+1):func(px,py,pz)", "", "COLZ")
```

Exercise 2: read a dataset and fill a histogram (\Rightarrow tree.C)

```
#include "TFile.h"
#include "TTree.h"
#include "TH2.h"
#include "TRandom.h"

void read_tree()
{
    TFile *infile = new TFile("tree_C.root", "READ");
    TTree *tree = (TTree*)infile->Get("tree");
    Float_t px, py, pz;
    Double_t random;
    Int_t ev;
    tree->SetBranchAddress("px",&px);
    tree->SetBranchAddress("py",&py);
    tree->SetBranchAddress("pz",&pz);
    tree->SetBranchAddress("random",&random);
    tree->SetBranchAddress("ev",&ev);
}
```

```
TH1F *hpx = new TH1F("hpx","px distribution",100,-3,3);
TH2F *hpxpy = new TH2F("hpxpy","py vs px",30,-3,3,30,-3,3);

Long64_t nentries = tree->GetEntries();
for (Long64_t i = 0; i < nentries; i++) {
    tree->GetEntry(i);
    hpx->Fill(px);
    hpxpy->Fill(px,py);
}

hpx->Draw("HISTE");
TFile* outfile = new TFile("histos.root", "RECREATE");
hpx->Write();
outfile->Close();
}
```

Exercise 2: read a dataset and fill a histogram (⇒ tree.C)

```
#include "TFile.h"
#include "TTree.h"
#include "TH2.h"
#include "TRandom.h"
```

```
void read_tree()
{
```

```
    TFile *infile = new TFile("tree_C.root", "READ");
    TTree *tree = (TTree*)infile->Get("tree");
    Float_t px, py, pz;
    Double_t random;
    Int_t ev;
    tree->SetBranchAddress("px",&px);
    tree->SetBranchAddress("py",&py);
    tree->SetBranchAddress("pz",&pz);
    tree->SetBranchAddress("random",&random);
    tree->SetBranchAddress("ev",&ev);
```

This is analogous to make_tree() with the replacements:

"RECREATE" ⇒ "READ"

tree->Branch(...) ⇒ tree->SetBranchAddress(...)

```
TH1F *hpx = new TH1F("hpx","px distribution",100,-3,3);
TH2F *hpxpy = new TH2F("hpxpy","py vs px",30,-3,3,30,-3,3);
```

```
Long64_t nentries = tree->GetEntries();
for (Long64_t i = 0; i < nentries; i++) {
    tree->GetEntry(i);
    hpx->Fill(px);
    hpxpy->Fill(px,py);
}
```

```
hpx->Draw("HISTE");
TFile* outfile = new TFile("histos.root", "RECREATE");
hpx->Write();
outfile->Close();
```

```
}
```

Exercise 2: read a dataset and fill a histogram (\Rightarrow tree.C)

```
#include "TFile.h"
#include "TTree.h"
#include "TH2.h"
#include "TRandom.h"
```

```
void read_tree()
{
```

```
TFile *infile = new TFile("tree_C.root", "READ");
TTree *tree = (TTree*)infile->Get("tree");
Float_t px, py, pz;
Double_t random;
Int_t ev;
tree->SetBranchAddress("px",&px);
tree->SetBranchAddress("py",&py);
tree->SetBranchAddress("pz",&pz);
tree->SetBranchAddress("random",&random);
tree->SetBranchAddress("ev",&ev);
```

We define 1D and 2D histograms to be filled with the TTree content

```
TH1F *hpx = new TH1F("hpx","px distribution",100,-3,3);
TH2F *hpxpy = new TH2F("hpxpy","py vs px",30,-3,3,30,-3,3);
```

```
Long64_t nentries = tree->GetEntries();
for (Long64_t i = 0; i < nentries; i++) {
    tree->GetEntry(i);
    hpx->Fill(px);
    hpxpy->Fill(px,py);
}
```

```
hpx->Draw("HISTE");
TFile* outfile = new TFile("histos.root", "RECREATE");
hpx->Write();
outfile->Close();
```

Draw a bar histogram ("HIST") with Poisson error ("E")

Histogram persistently written into file, e.g. for future use

Exercise 2: read a dataset and fill a histogram (⇒ tree.C)

```
#include "TFile.h"
#include "TTree.h"
#include "TH2.h"
#include "TRandom.h"
```

```
void read_tree()
{
```

```
  TFile *infile = new TFile("tree_C.root", "READ");
  TTree *tree = (TTree*)infile->Get("tree");
  Float_t px, py, pz;
  Double_t random;
  Int_t ev;
  tree->SetBranchAddress("px",&px);
  tree->SetBranchAddress("py",&py);
  tree->SetBranchAddress("pz",&pz);
  tree->SetBranchAddress("random",&random);
  tree->SetBranchAddress("ev",&ev);
```

```
  TH1F *hpx = new TH1F("hpx","px distribution",100,-3,3);
  TH2F *hpxpy = new TH2F("hpxpy","py vs px",30,-3,3,30,-3,3);
```

```
  Long64_t nentries = tree->GetEntries();
  for (Long64_t i = 0; i < nentries; i++) {
    tree->GetEntry(i);
    hpx->Fill(px);
    hpxpy->Fill(px,py);
  }
```

```
  hpx->Draw("HISTE");
  TFile* outfile = new TFile("histos.root", "RECREATE");
  hpx->Write();
  outfile->Close();
```

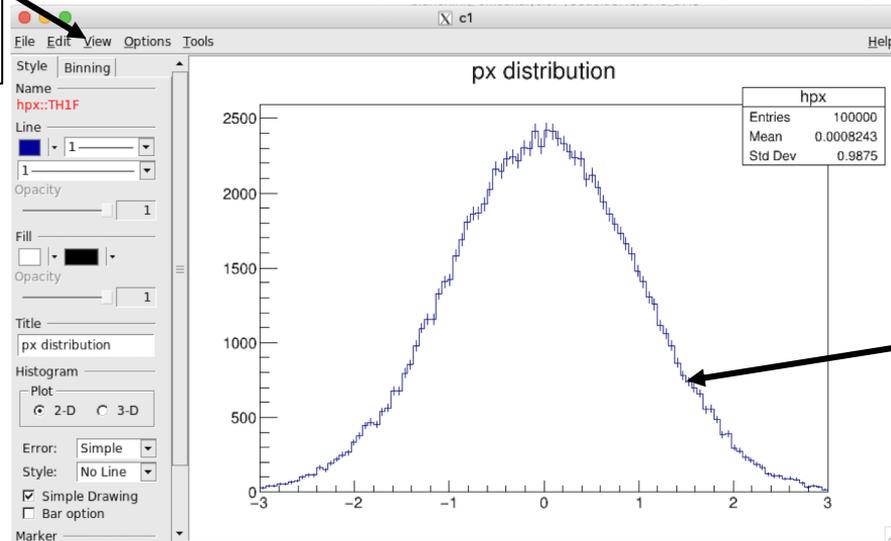
Start the “event” loop. At each iterate i , the `GetEntry(i)` command will read data row i for all the “addressed” branches.

Not-addressed branches are NOT read (big speed-up when partial data needed)

A simple 1D fit to a binned data set (\Rightarrow tree.C)

- Run `read_tree()`
- The default TCanvas is displayed showing `hpx`

On the top-left, select
“View” \rightarrow “Editor”



Right-click on any point
of the histogram and
choose “Fit Panel”

The Fit Panel

Fit function
(pre-defined or user-defined)

Loss function
(χ^2 or binned likelihood)

Fit options
Click on **SAME** so that fit result is visualized

Adjustable fit range

The screenshot shows the 'Fit Panel' window with the following settings:

- Data Set: TH1F::hpx
- Fit Function Type: Predef-1D, gaus
- Operation: Nop (selected), Add, NormAdd, Conv
- Selected: gaus
- General tab: Minimization
- Fit Settings: Method: Chi-square, Robust: 0.95
- Fit Options: Integral, Best errors, All weights = 1, Empty bins, weights=1, Use range, Improve fit results, Add to list, Use Gradient
- Draw Options: SAME (checked), No drawing, Do not store/draw
- X range: -3.00 to 3.00
- Buttons: Update, Fit, Reset, Close
- Status bar: TH1F::hpx | LIB Minuit | MIGRAD | ltr: 0 | Prn: DEF

Minimizer

- **Minuit**: Migrad, Simplex, Fumili
- **GSL**: conjugate-gradient (FR, PR) Lavenberg-Marquardt, Steepest descent

Choose:

Type -> Predef-1D -> gaus
Minimization -> Minuit -> MIGRAD

Click on Fit

Saving graphic data into a .C file

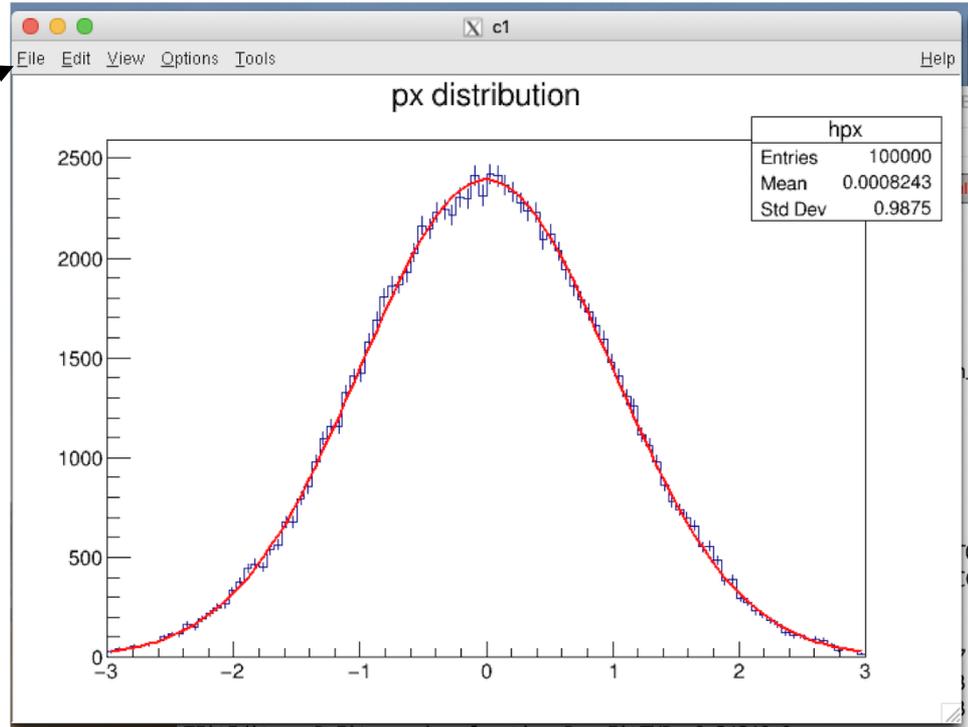
You can customize the plot as you wish.
Then: “File” -> “Save As...” to save it in graphic form.

Select the “.C” format, and save it as example.C

Now do:

```
root[1] .q
```

```
> root -l example.C
```



◆ A simple 1D fit to a binned data set

This way of doing a fit is clear, but inefficient (shown only for illustration!)

In real life applications (e.g. $\gg 1$ histograms, multiple fit options, complicated functions...), all of these operations will be coded in a C++ macro and run in batch mode:

```
> root -b fit.C
```

Homework: write your own version of `fit.C`

Hint: you should use the `.Fit()` method of the `TH1F` class

Exercise 3: make_tree() revisited (\Rightarrow tree.py)

```
import ROOT
import numpy as np

def make_tree(nevents):
    outfile = ROOT.TFile("tree_py.root", "RECREATE")
    tree = ROOT.TTree("tree", "A simple Tree")
    px = np.empty((1), dtype="float32")
    py = np.empty((1), dtype="float32")
    pz = np.empty((1), dtype="float32")
    random = np.empty((1), dtype="float64")
    ev = np.empty((1), dtype="int32")
    tree.Branch("px", px, "px/F")
    tree.Branch("py", py, "py/F")
    tree.Branch("pz", pz, "pz/F")
    tree.Branch("random", random, "random/D")
    tree.Branch("ev", ev, "ev/I")
    for i in range(nevents):
        px[0] = np.random.normal()
        py[0] = np.random.normal()
        pz[0] = px[0]**2 + py[0]**2
        random[0] = np.random.random_sample()
        ev[0] = i
    tree.Fill()
    outfile.Write()
    return (outfile), tree
```

```
if __name__ == '__main__':
    _, tree = make_tree(100000)
    array, labels = tree.AsMatrix(return_labels=True)
```

Exercise 3: make_tree() revisited (⇒ tree.py)

```
import ROOT
import numpy as np
```

```
def make_tree(nevents):
    outfile = ROOT.TFile("tree_py.root", "RECREATE")
    tree = ROOT.TTree("tree", "A simple Tree")
    px = np.empty((1), dtype="float32")
    py = np.empty((1), dtype="float32")
    pz = np.empty((1), dtype="float32")
    random = np.empty((1), dtype="float64")
    ev = np.empty((1), dtype="int32")
    tree.Branch("px", px, "px/F")
    tree.Branch("py", py, "py/F")
    tree.Branch("pz", pz, "pz/F")
    tree.Branch("random", random, "random/D")
    tree.Branch("ev", ev, "ev/I")
    for i in range(nevents):
        px[0] = np.random.normal()
        py[0] = np.random.normal()
        pz[0] = px[0]**2 + py[0]**2
        random[0] = np.random.random_sample()
        ev[0] = i
    tree.Fill()
    outfile.Write()
    return (outfile), tree
```

```
if __name__ == '__main__':
    _, tree = make_tree(100000)
    array, labels = tree.AsMatrix(return_labels=True)
```

That's it! From now on, any ROOT class **T*** accessible using **ROOT.T***

numpy or array only needed for writing branches

Exercise 3: make_tree() revisited (\Rightarrow tree.py)

```
import ROOT
import numpy as np
```

```
def make_tree(nevents):
    outfile = ROOT.TFile("tree_py.root", "RECREATE")
    tree = ROOT.TTree("tree", "A simple Tree")
    px = np.empty((1), dtype="float32")
    py = np.empty((1), dtype="float32")
    pz = np.empty((1), dtype="float32")
    random = np.empty((1), dtype="float64")
    ev = np.empty((1), dtype="int32")
    tree.Branch("px", px, "px/F")
    tree.Branch("py", py, "py/F")
    tree.Branch("pz", pz, "pz/F")
    tree.Branch("random", random, "random/D")
    tree.Branch("ev", ev, "ev/I")
    for i in range(nevents):
        px[0] = np.random.normal()
        py[0] = np.random.normal()
        pz[0] = px[0]**2 + py[0]**2
        random[0] = np.random.random_sample()
        ev[0] = i
    tree.Fill()
    outfile.Write()
    return (outfile), tree
```

```
if __name__ == '__main__':
    _, tree = make_tree(100000)
    array, labels = tree.AsMatrix(return_labels=True)
```



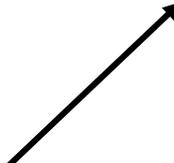
Same as before, with all
the benefits of Python

Exercise 3: make_tree() revisited (\Rightarrow tree.py)

```
import ROOT
import numpy as np

def make_tree(nevents):
    outfile = ROOT.TFile("tree_py.root", "RECREATE")
    tree = ROOT.TTree("tree", "A simple Tree")
    px = np.empty((1), dtype="float32")
    py = np.empty((1), dtype="float32")
    pz = np.empty((1), dtype="float32")
    random = np.empty((1), dtype="float64")
    ev = np.empty((1), dtype="int32")
    tree.Branch("px", px, "px/F")
    tree.Branch("py", py, "py/F")
    tree.Branch("pz", pz, "pz/F")
    tree.Branch("random", random, "random/D")
    tree.Branch("ev", ev, "ev/I")
    for i in range(nevents):
        px[0] = np.random.normal()
        py[0] = np.random.normal()
        pz[0] = px[0]**2 + py[0]**2
        random[0] = np.random.random_sample()
        ev[0] = i
    tree.Fill()
    outfile.Write()
    return (outfile), tree
```

```
if __name__ == '__main__':
    _, tree = make_tree(100000)
    array, labels = tree.AsMatrix(return_labels=True)
```



A nice feature: automatic conversion
TTree \rightarrow numpy.array(nevents,nbranches)
(working in multithread mode, if supported)

Exercise 3: make_tree() revisited (\Rightarrow tree.py)

```
import ROOT
import numpy as np

def make_tree(nevents):
    outfile = ROOT.TFile("tree_py.root", "RECREATE")
    tree = ROOT.TTree("tree", "A simple Tree")
    px = np.empty((1), dtype="float32")
    py = np.empty((1), dtype="float32")
    pz = np.empty((1), dtype="float32")
    random = np.empty((1), dtype="float64")
    ev = np.empty((1), dtype="int32")
    tree.Branch("px", px, "px/F")
    tree.Branch("py", py, "py/F")
    tree.Branch("pz", pz, "pz/F")
    tree.Branch("random", random, "random/D")
    tree.Branch("ev", ev, "ev/I")
    for i in range(nevents):
        px[0] = np.random.normal()
        py[0] = np.random.normal()
        pz[0] = px[0]**2 + py[0]**2
        random[0] = np.random.random_sample()
        ev[0] = i
    tree.Fill()
    outfile.Write()
    return (outfile, tree)
```

```
if __name__ == '__main__':
    _, tree = make_tree(100000)
    array, labels = tree.AsMatrix(return_labels=True)
```

Caveats:

PyROOT can be much slower than compiled C++ (see *e.g. the two examples just discussed*)

Handling of memory sometimes problematic. Extra care needed to avoid memory leaks.

Exercise 3: `make_tree()` revisited (\Rightarrow `tree.py`)

Let's run it:

```
> python tree.py 10
```

```
> python tree.py 100000
```

Now, let's modify `tree.py` so that the output tree also contains variable-length arrays of floats...

N.B.: conversion into `numpy` array will fail due to array-like branch

Exercise 4: a tree with variable-length branches (\Rightarrow tree_array.py)

```
import ROOT
import numpy as np

def make_tree(nevents):
    outfile = ROOT.TFile("tree_py.root", "RECREATE")
    tree = ROOT.TTree("tree", "A simple Tree")
    px = np.empty((1), dtype="float32")
    py = np.empty((1), dtype="float32")
    pz = np.empty((1), dtype="float32")
    random = np.empty((1), dtype="float64")
    ev = np.empty((1), dtype="int32")
    nHits = np.empty((1), dtype="int32")
    hits = np.empty((100), dtype="float32")
    tree.Branch("px", px, "px/F")
    tree.Branch("py", py, "py/F")
    tree.Branch("pz", pz, "pz/F")
    tree.Branch("random", random, "random/D")
    tree.Branch("ev", ev, "ev/I")
    tree.Branch("nHits", nHits, "nHits/I")
    tree.Branch("hits", hits, "hits[nHits]/F")
```

```
for i in range(nevents):
    px[0] = np.random.normal()
    py[0] = np.random.normal()
    pz[0] = px[0]**2 + py[0]**2
    random[0] = np.random.random_sample()
    ev[0] = i
    nHits[0] = 2 if i%2==0 else 4
    for h in range(nHits[0]):
        hits[h] = np.random.randint(0,20)
    tree.Fill()
outfile.Write()
return (outfile), tree
```

Exercise 5: ROOT mathematical environment (\Rightarrow minimizer.C)

ROOT comes with a native mathematical environment

- **Linear algebra:** matrix inversion, eigendecomposition, determinant, matrix-matrix and matrix-vector multiplication.
- **N-dimensional integration:** MC integration methods (VEGAS, Adaptive, Miser, Gauss-Legendre (1D))
- **N-dimensional minimization:** Minuit2 (re-written from original FORTRAN code by F. James) and wrapper to GSL minimizers

Exercise 5: ROOT mathematical environment (\Rightarrow minimizer.C)

```
#include "Math/Minimizer.h"
#include "Math/Factory.h"
#include "Math/Functor.h"
#include "TRandom3.h"
#include "Math/IntegratorMultiDim.h"

const int NDIM = 4;

TMatrixD B = THilbertMatrixD(NDIM,NDIM);

double grad[NDIM] = {};
TVectorD g(NDIM, grad);
const double f0 = 1.0;

double Quadratic(const double *xx)
{
    TVectorD x(NDIM, xx);
    return f0 + g*x + 0.5*(x*(B*x));
}

void minimizer(const char * minName = "Minuit", const char *algoName =
"Mgrad"){
    TRandom3 ran(1234);
    double gmin = -1.;
    double gmax = +1.;

    for(unsigned int i=0 ; i<NDIM; ++i){
        double r = ran.Rndm();
        g[i] = gmin*r + gmax*(1-r);
    }

    TVectorD eig(NDIM);
    TMatrixD eigs = B.EigenVectors(eig);
    Double_t det = B.Determinant();
```

```
ROOT::Math::Minimizer* minimum = ROOT::Math::Factory::CreateMinimizer(minName,
algoName);
minimum->SetMaxFunctionCalls(1000000);
minimum->SetTolerance(0.001);
minimum->SetPrintLevel(1);

ROOT::Math::Functor f(&Quadratic, NDIM);
minimum->SetFunction(f);

double step[NDIM] = {};
for(unsigned int i=0 ; i<NDIM; ++i) step[i] += 0.01;
double start[NDIM] = {};
for(unsigned int i=0 ; i<NDIM; ++i){
    minimum->SetVariable(i, Form("x%d",i), start[i], step[i]);
}

minimum->Minimize();
const double *xs = minimum->X();

std::cout << std::endl;
std::cout << "NUMERICAL: f(";
for(unsigned int i=0 ; i<NDIM; ++i) std::cout << xs[i] << ", ";
std::cout << ") : " << minimum->MinValue() << std::endl;

TVectorD x0(NDIM, start);
TMatrixD Binv(B);
TVectorD xs_ana = x0 - Binv.InvertFast()*(B*x0 + g);
std::cout << "ANALYTICAL: f(";
for(unsigned int i=0 ; i<NDIM; ++i) std::cout << xs_ana[i] << ", ";
std::cout << ") : " << Quadratic(xs_ana.GetMatrixArray()) << std::endl;

return;
}
```

Exercise 5: ROOT mathematical environment (\Rightarrow minimizer.C)

```
#include "Math/Minimizer.h"  
#include "Math/Factory.h"  
#include "Math/Functor.h"  
#include "TRandom3.h"  
#include "Math/IntegratorMultiDim.h"
```

```
const int NDIM = 4;
```

```
TMatrixD B = THilbertMatrixD(NDIM,NDIM);
```

```
double grad[NDIM] = {};  
TVectorD g(NDIM, grad);  
const double f0 = 1.0;
```

```
double Quadratic(const double *xx)  
{  
    TVectorD x(NDIM, xx);  
    return f0 + g*x + 0.5*(x*(B*x));  
}
```

```
void minimizer(const char * minName = "Minuit", const  
char *algoName = "Migrad"){
```

```
    TRandom3 ran(1234);  
    double gmin = -1.;  
    double gmax = +1.;
```

```
    for(unsigned int i=0 ; i<NDIM; ++i){  
        double r = ran.Rndm();  
        g[i] = gmin*r + gmax*(1-r);  
    }
```

Use an ill-conditioned Hessian matrix
to make the task more challenging

The objective function we wish to
minimize.
xx[i] is i -th variable

Create non-zero gradient to
make the solution non-trivial

Exercise 5: ROOT mathematical environment (\Rightarrow minimizer.C)

Check positive-definiteness of the Hessian matrix

```
TVectorD eig(NDIM);  
TMatrixD eigs = B.EigenVectors(eig);  
Double_t det = B.Determinant();
```

Use ROOT::Math::Factory to instantiate the minimizer

```
ROOT::Math::Minimizer* minimum =  
ROOT::Math::Factory::CreateMinimizer(minName, algoName);  
minimum->SetMaxFunctionCalls(1000000);  
minimum->SetTolerance(0.001);  
minimum->SetPrintLevel(1);
```

Define which function to minimize

```
ROOT::Math::Functor f( &Quadratic, NDIM);  
minimum->SetFunction(f);
```

Declare variable and suitable starting values & initial step

```
double step[NDIM] = {};  
for(unsigned int i=0 ; i<NDIM; ++i) step[i] += 0.01;  
double start[NDIM] = {};  
for(unsigned int i=0 ; i<NDIM; ++i){  
    minimum->SetVariable(i, Form("x%d",i), start[i], step[i]);  
}
```

Exercise 5: ROOT mathematical environment (\Rightarrow minimizer.C)

```
minimum->Minimize();  
const double *xs = minimum->X();
```

Start the minimizer

```
std::cout << std::endl;  
std::cout << "NUMERICAL: f(";  
for(unsigned int i=0 ; i<NDIM; ++i) std::cout << xs[i] << ", ";  
std::cout << "): " << minimum->MinValue() << std::endl;
```

Retrieve the information
about the minimum

```
TVectorD x0(NDIM, start);  
TMatrixD Binv(B);  
TVectorD xs_ana = x0 - Binv.InvertFast()*(B*x0 + g);  
std::cout << "ANALYTICAL: f(";  
for(unsigned int i=0 ; i<NDIM; ++i) std::cout << xs_ana[i] << ", ";  
std::cout << "): " << Quadratic(xs_ana.GetMatrixArray()) << std::endl;
```

Alternatively, find the
solution by one Newton step

Evaluate the objective
function at the analytical
solution

Exercise 5: ROOT mathematical environment (\Rightarrow minimizer.C)

```
double xL[NDIM] = {};  
double xU[NDIM] = {};  
for(unsigned int i=0 ; i<NDIM; ++i) xL[i] = -1.0;  
for(unsigned int i=0 ; i<NDIM; ++i) xU[i] = +1.0;
```

Integration range

```
double val = 0.0;  
ROOT::Math::IntegratorMultiDim ig1(ROOT::Math::IntegrationMultiDim::kVEGAS);  
ig1.SetFunction(f);  
val = ig1.Integral(xL,xU);  
return;  
}
```

Several MC algorithms
available.
Unique interface.

Integrate the
function in a box

Exercise 5: ROOT mathematical environment (\Rightarrow minimizer.C)

Let's run it:

```
> root -l
root[1] .L minimizer.C
root[2] minimizer("Minuit2","migrad") // quasi-Newton line-search with Fletcher's switching rank-2 update
root[3] minimizer("Minuit2","simplex") // Nelder-Mead simplex algorithm
root[4] minimizer("GSLMultiMin","conjugatefr") // Fletcher-Reeves conjugate-gradient line-search
root[5] minimizer("GSLMultiMin","conjugatepr") // Poljak-Ribiere conjugate-gradient line-search
root[6] minimizer("GSLMultiMin","bfgs2") // quasi-Newton method with BFGS rank-2 update
root[7] minimizer("GSLMultiMin","steepestdescent")// steepest-descent line search
```

You can try two functions: "Quadratic" (NDIM<7) and "Rosenbrock" (NDIM>100)

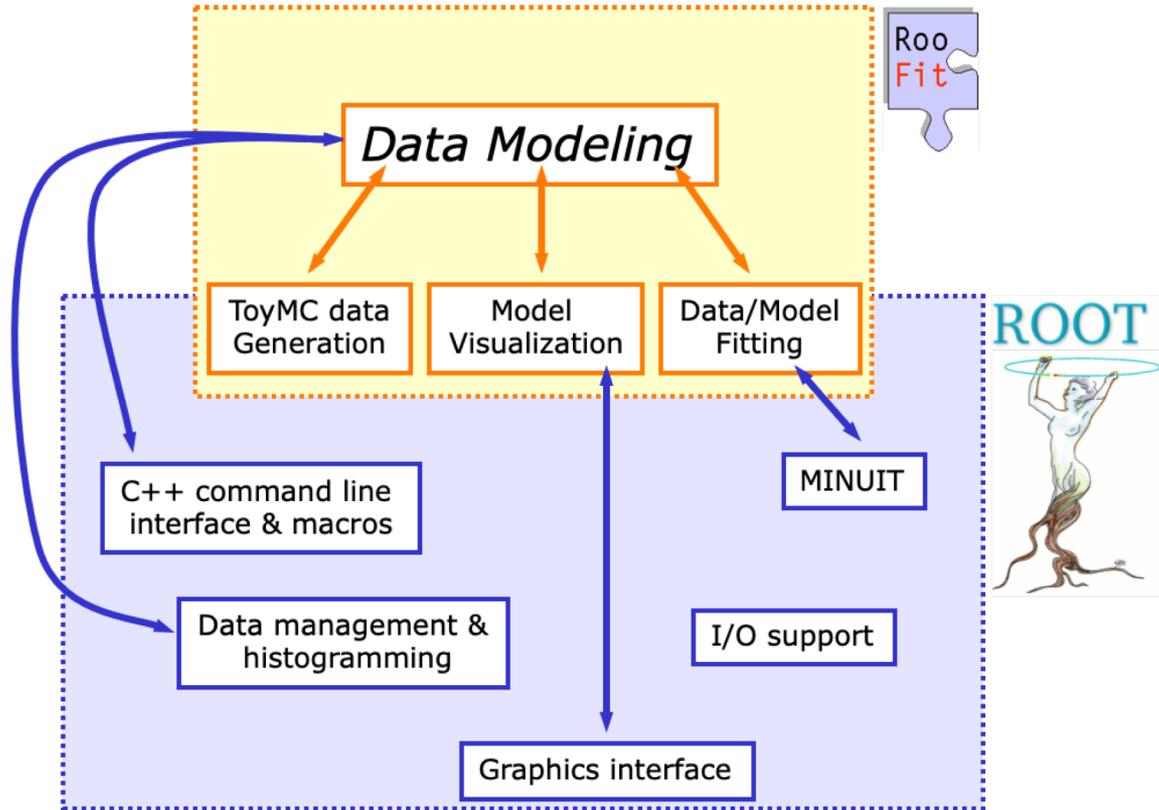
Roofit: a ROOT package for statistical analysis

- **ROOT has some limitations when dealing with complicated fit**
 - Standard ROOT function framework insufficient to handle complicated functions
 - P.d.f.'s are normalized densities, not just functions
 - Computation performances important when $\text{NDIM} \gg 1$, unbinned data, many events, ...
- **You can write a specific fit using ROOT interface to Minuit (\Rightarrow minimizer.C)**
 - can requires a lot of coding and *ad hoc* optimization

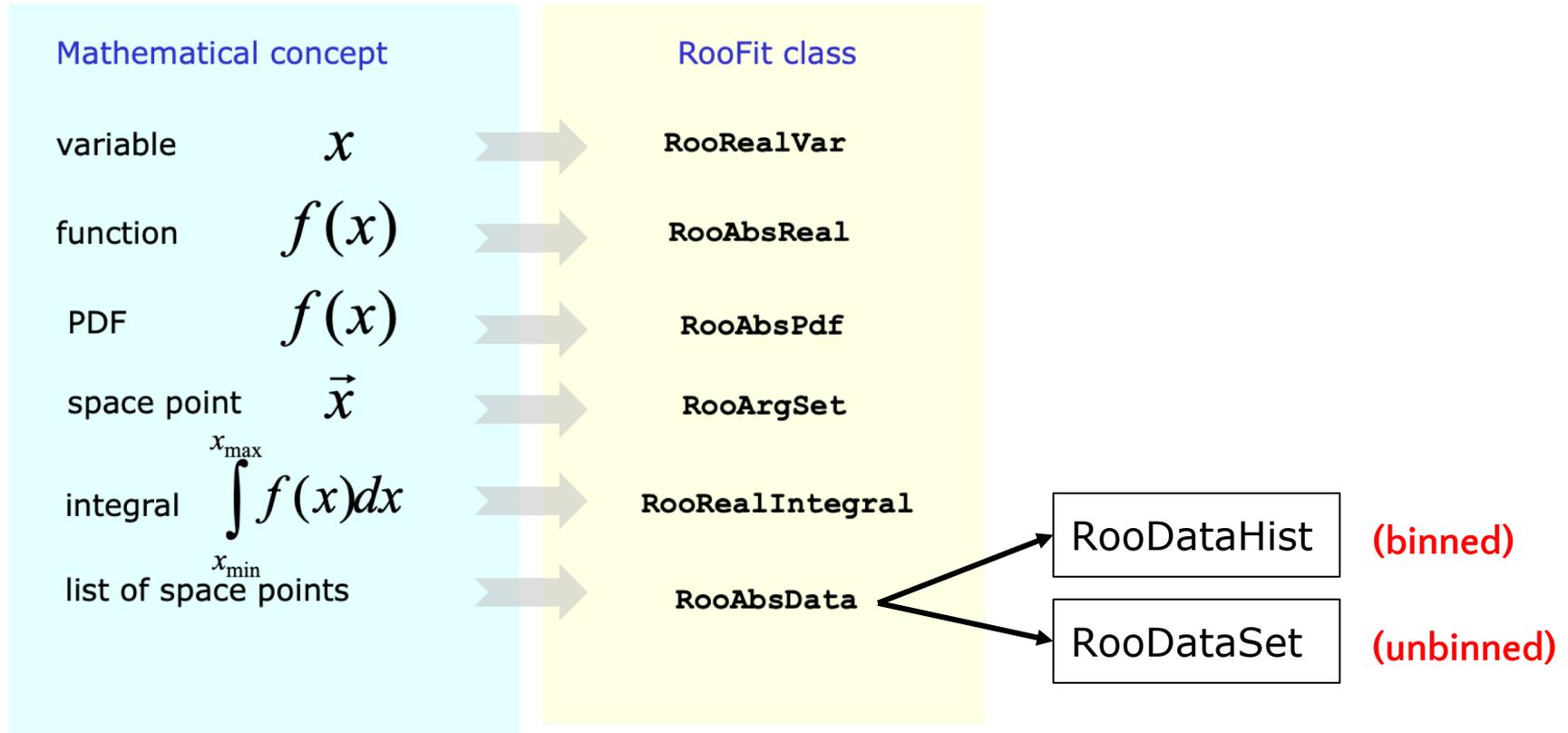
\Rightarrow **Roofit**

- Interface to Minuit2 transparent to the user
- Many precompiled physics-inspired p.d.f.'s
- Takes care of p.d.f. normalization, variable marginalization, conditioning, simultaneous fit.
Using optimizations whenever possible
- Automatization of profile-likelihood scans, likelihood contours, GoF, MC studies, ...

Roofit: a ROOT package for statistical analysis



Roofit: a ROOT package for statistical analysis



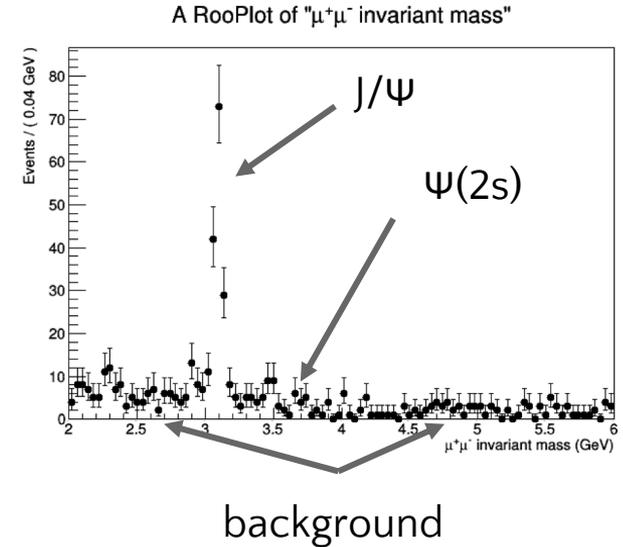
A more sophisticated fit: measuring a cross section

- A sample of di-muon events is collected and their invariant mass is measured. Three processes:
 - J/ψ , with a mass of 3.096 GeV and FWHM ~ 1%
 - $\psi(2s)$ with a mass of 3.686 GeV, same width as J/ψ
 - smooth and broad combinatorial background

- What is the cross section σ of $\psi(2s)$?

$$\sigma = N / (L \epsilon), \quad N = \text{number of measured } \psi(2s) \text{ (TBD)}$$
$$L = \text{integrated luminosity (0.64/pb)}$$
$$\epsilon = \text{reconstruction efficiency (75\%)}$$

- The data is a RooDataSet (\Rightarrow DataSet_lowstat.root) containing the di-muon mass of 500 events.



Exercise 6: fitting with RooFit (\Rightarrow roofit.py)

```
import ROOT

fInput = ROOT.TFile("DataSet_lowstat.root")
dataset = fInput.Get("data")

mass = ROOT.RooRealVar("mass","mumu mass", 2.0,
6.0,"GeV")

meanJpsi = ROOT.RooRealVar("meanJpsi","The mean of the Jpsi
Gaussian",3.1,2.8,3.2)
sigmaJpsi = ROOT.RooRealVar("sigmaJpsi","The width of the Jpsi
Gaussian",0.3,0.0001,1.)
alphaJpsi = ROOT.RooRealVar("alphaJpsi","The alpha of the Jpsi
Gaussian",1.5,-5.,5.)
nJpsi = ROOT.RooRealVar("nJpsi","The alpha of the Jpsi
Gaussian",1.5,0.5,5.)

CBJpsi = ROOT.RooCBSShape("CBJpsi","The Jpsi Crystall
Ball",mass,meanJpsi,sigmaJpsi,alphaJpsi,nJpsi)
```

```
meanpsi2S = ROOT.RooRealVar("meanpsi2S","The mean of
the psi(2S) Gaussian",3.7,3.65,3.75)
gausspsi2S = ROOT.RooGaussian("gausspsi2S","The psi(2S)
Gaussian",mass,meanpsi2S,sigmaJpsi)

a1 = ROOT.RooRealVar("a1","The a1 of background",-0.7,-
2.,2.)
a2 = ROOT.RooRealVar("a2","The a2 of background",0.3,-
2.,2.)
a3 = ROOT.RooRealVar("a3","The a3 of background",-0.03,-
2.,2.)
backgroundPDF =
ROOT.RooChebychev("backgroundPDF","The background
PDF",mass,ROOT.RooArgList(a1,a2,a3))
```

Exercise 6: fitting with RooFit (\Rightarrow roofit.py)

Get the data (same I/O than ROOT!)

```
import ROOT
```

```
fInput = ROOT.TFile("DataSet_lowstat.root")  
dataset = fInput.Get("data")
```

```
mass = ROOT.RooRealVar("mass","mumu mass", 2.0,  
6.0,"GeV")
```

```
meanJpsi = ROOT.RooRealVar("meanJpsi","The mean of the Jpsi  
Gaussian",3.1,2.8,3.2)  
sigmaJpsi = ROOT.RooRealVar("sigmaJpsi","The width of the Jpsi  
Gaussian",0.3,0.0001,1.)  
alphaJpsi = ROOT.RooRealVar("alphaJpsi","The alpha of the Jpsi  
Gaussian",1.5,-5.,5.)  
nJpsi = ROOT.RooRealVar("nJpsi","The alpha of the Jpsi  
Gaussian",1.5,0.5,5.)
```

```
CBJpsi = ROOT.RooCBSShape("CBJpsi","The Jpsi Crystall  
Ball",mass,meanJpsi,sigmaJpsi,alphaJpsi,nJpsi)
```

```
meanpsi2S = ROOT.RooRealVar("meanpsi2S","The mean of  
the psi(2S) Gaussian",3.7,3.65,3.75)  
gausspsi2S = ROOT.RooGaussian("gausspsi2S","The psi(2S)  
Gaussian",mass,meanpsi2S,sigmaJpsi)
```

```
a1 = ROOT.RooRealVar("a1","The a1 of background",-0.7,-  
2.,2.)  
a2 = ROOT.RooRealVar("a2","The a2 of background",0.3,-  
2.,2.)  
a3 = ROOT.RooRealVar("a3","The a3 of background",-0.03,-  
2.,2.)  
backgroundPDF =  
ROOT.RooChebychev("backgroundPDF","The background  
PDF",mass,ROOT.RooArgList(a1,a2,a3))
```

"data" contains a column with title "mass"
(N.B. data imported by name, so they have to match)

Exercise 6: fitting with RooFit (\Rightarrow roofit.py)

```
import ROOT

fInput = ROOT.TFile("DataSet_lowstat.root")
dataset = fInput.Get("data")

mass = ROOT.RooRealVar("mass","mumu mass", 2.0,
6.0,"GeV")

meanJpsi = ROOT.RooRealVar("meanJpsi","The mean of the Jpsi
Gaussian",3.1,2.8,3.2)
sigmaJpsi = ROOT.RooRealVar("sigmaJpsi","The width of the Jpsi
Gaussian",0.3,0.0001,1.)
alphaJpsi = ROOT.RooRealVar("alphaJpsi","The alpha of the Jpsi
Gaussian",1.5,-5.,5.)
nJpsi = ROOT.RooRealVar("nJpsi","The alpha of the Jpsi
Gaussian",1.5,0.5,5.)
```

```
CBJpsi = ROOT.RooCBSShape("CBJpsi","The Jpsi Crystall
Ball",mass,meanJpsi,sigmaJpsi,alphaJpsi,nJpsi)
```

P.d.f. for the J/Ψ (\Rightarrow Crystal Ball function)

A simpler (\Rightarrow Gaussian) function for $\Psi(2s)$

```
meanpsi2S = ROOT.RooRealVar("meanpsi2S","The mean of
the psi(2S) Gaussian",3.7,3.65,3.75)
gausspsi2S = ROOT.RooGaussian("gausspsi2S","The psi(2S)
Gaussian",mass,meanpsi2S,sigmaJpsi)
```

```
a1 = ROOT.RooRealVar("a1","The a1 of background",-0.7,-
2.,2.)
a2 = ROOT.RooRealVar("a2","The a2 of background",0.3,-
2.,2.)
a3 = ROOT.RooRealVar("a3","The a3 of background",-0.03,-
2.,2.)
backgroundPDF =
ROOT.RooChebychev("backgroundPDF","The background
PDF",mass,ROOT.RooArgList(a1,a2,a3))
```

An empirical (\Rightarrow polynomial) function for the background

Exercise 6: fitting with RooFit (\Rightarrow roofit.py)

```
NJpsi = ROOT.RooRealVar("NJpsi","The Jpsi signal
events",1500.,0.1,10000.)
Nbkg = ROOT.RooRealVar("Nbkg","The bkg
events",5000.,0.1,50000.)

eff_psi = ROOT.RooRealVar("eff_psi","The psi
efficiency",0.75,0.00001,1.)
lumi_psi = ROOT.RooRealVar("lumi_psi","The CMS
luminosity",0.64,0.00001,50.,"pb-1")
cross_psi = ROOT.RooRealVar("cross_psi","The psi
xsec",3.,0.,40.,"pb")
Npsi =
ROOT.RooFormulaVar("Npsi","@0*@1*@2",ROOT.RooArgList(eff
_psi,lumi_psi,cross_psi))
eff_psi.setConstant(1)
lumi_psi.setConstant(1)

totPDF = ROOT.RooAddPdf("totPDF","The total
PDF",ROOT.RooArgList(CBJpsi,gausspsi2S,backgroundPDF),ROOT
.RooArgList(NJpsi,Npsi,Nbkg))

totPDF.fitTo(dataset, ROOT.RooFit.Extended(1))
```

```
xframe = mass.frame()
dataset.plotOn(xframe)
totPDF.plotOn(xframe)
totPDF.plotOn(xframe,
ROOT.RooFit.Components("backgroundPDF"),
ROOT.RooFit.LineStyle(ROOT.kDashed),
ROOT.RooFit.LineColor(ROOT.kRed))

c1 = ROOT.TCanvas()
xframe.Draw()
c1.SaveAs("exercise_0.png")

fOutput =
ROOT.TFile("Workspace_mumufit.root","RECREATE")
fInput.cd()
ws = ROOT.RooWorkspace("ws")
getattr(ws,'import')(totPDF)
getattr(ws,'import')(dataset)
ws.writeToFile("Workspace_mumufit.root")
del ws
fOutput.Write()
fOutput.Close()
```

Exercise 6: fitting with RooFit (\Rightarrow roofit.py)

Total yields for changing the relative S & B fractions

```
NJpsi ← ROOT.RooRealVar("NJpsi","The Jpsi signal  
events",1500.,0.1,10000.)
```

```
Nbkg = ROOT.RooRealVar("Nbkg","The bkg  
events",5000.,0.1,50000.)
```

```
eff_psi = ROOT.RooRealVar("eff_psi","The psi  
efficiency",0.75,0.00001,1.)
```

```
lumi_psi = ROOT.RooRealVar("lumi_psi","The CMS  
luminosity",0.64,0.00001,50.,"pb-1")
```

```
cross_psi = ROOT.RooRealVar("cross_psi","The psi  
xsec",3,0.,40.,"pb")
```

```
Npsi =
```

```
ROOT.RooFormulaVar("Npsi","@0*@1*@2",ROOT.RooArgList(eff  
_psi,lumi_psi,cross_psi))
```

```
eff_psi.setConstant(1)
```

```
lumi_psi.setConstant(1)
```

```
totPDF = ROOT.RooAddPdf("totPDF","The total  
PDF",ROOT.RooArgList(CBJpsi,gausspsi2S,backgroundPDF),ROOT  
.RooArgList(NJpsi,Npsi,Nbkg))
```

```
totPDF.fitTo(dataset, ROOT.RooFit.Extended(1))
```

```
xframe = mass.frame()  
dataset.plotOn(xframe)
```

$$-\log(L(\vec{p})) = -\sum_D \log(g(\vec{x}_i, \vec{p})) + N_{\text{exp}} - N_{\text{obs}} \log(N_{\text{exp}})$$

```
ROOT.RooFit.LineColor(ROOT.kRed))
```

```
c1 = ROOT.TCanvas()  
xframe.Draw()  
c1.SaveAs("exercise_0.png")
```

```
fOutput =  
ROOT.TFile("Workspace_mumufit.root","RECREATE")  
fInput.cd()  
ws = ROOT.RooWorkspace("ws")  
getattr(ws,'import')(totPDF)  
getattr(ws,'import')(dataset)  
ws.writeToFile("Workspace_mumufit.root")  
del ws  
fOutput.Write()  
fOutput.Close()
```

Total p.d.f. is S+B

Construct the NLL and minimize it w.r.t. all non-constant RooRealVar

Exercise 6: fitting with RooFit (\Rightarrow roofit.py)

```
NJpsi = ROOT.RooRealVar("NJpsi","The Jpsi signal
events",1500.,0.1,10000.)
Nbkg = ROOT.RooRealVar("Nbkg","The bkg
events",5000.,0.1,50000.)
```

```
eff_psi = ROOT.RooRealVar("eff_psi","The psi
efficiency",0.75,0.00001,1.)
lumi_psi = ROOT.RooRealVar("lumi_psi","The CMS
luminosity",0.64,0.00001,50.,"pb-1")
cross_psi = ROOT.RooRealVar("cross_psi","The psi
xsec",3.,0.,40.,"pb")
Npsi =
ROOT.RooFormulaVar("Npsi","@0*@1*@2",ROOT.RooArgList(eff
_psi,lumi_psi,cross_psi))
eff_psi.setConstant(1)
lumi_psi.setConstant(1)
```

```
totPDF = ROOT.RooAddPdf("totPDF","The total
PDF",ROOT.RooArgList(CBJpsi,gausspsi2S,backgroundPDF),ROOT
.RooArgList(NJpsi,Npsi,Nbkg))
```

```
totPDF.fitTo(dataset, ROOT.RooFit.Extended(1))
```

A fix for bad memory handling...

```
xframe = mass.frame()
dataset.plotOn(xframe)
totPDF.plotOn(xframe)
totPDF.plotOn(xframe,
ROOT.RooFit.Components("backgroundPDF"),
ROOT.RooFit.LineStyle(ROOT.kDashed),
ROOT.RooFit.LineColor(ROOT.kRed))
```

```
c1 = ROOT.TCanvas()
xframe.Draw()
c1.SaveAs("exercise_0.png")
```

```
fOutput =
ROOT.TFile("Workspace_mumufit.root","RECREATE")
fInput.cd()
ws = ROOT.RooWorkspace("ws")
getattr(ws,'import')(totPDF)
getattr(ws,'import')(dataset)
ws.writeToFile("Workspace_mumufit.root")
del ws
fOutput.Write()
fOutput.Close()
```

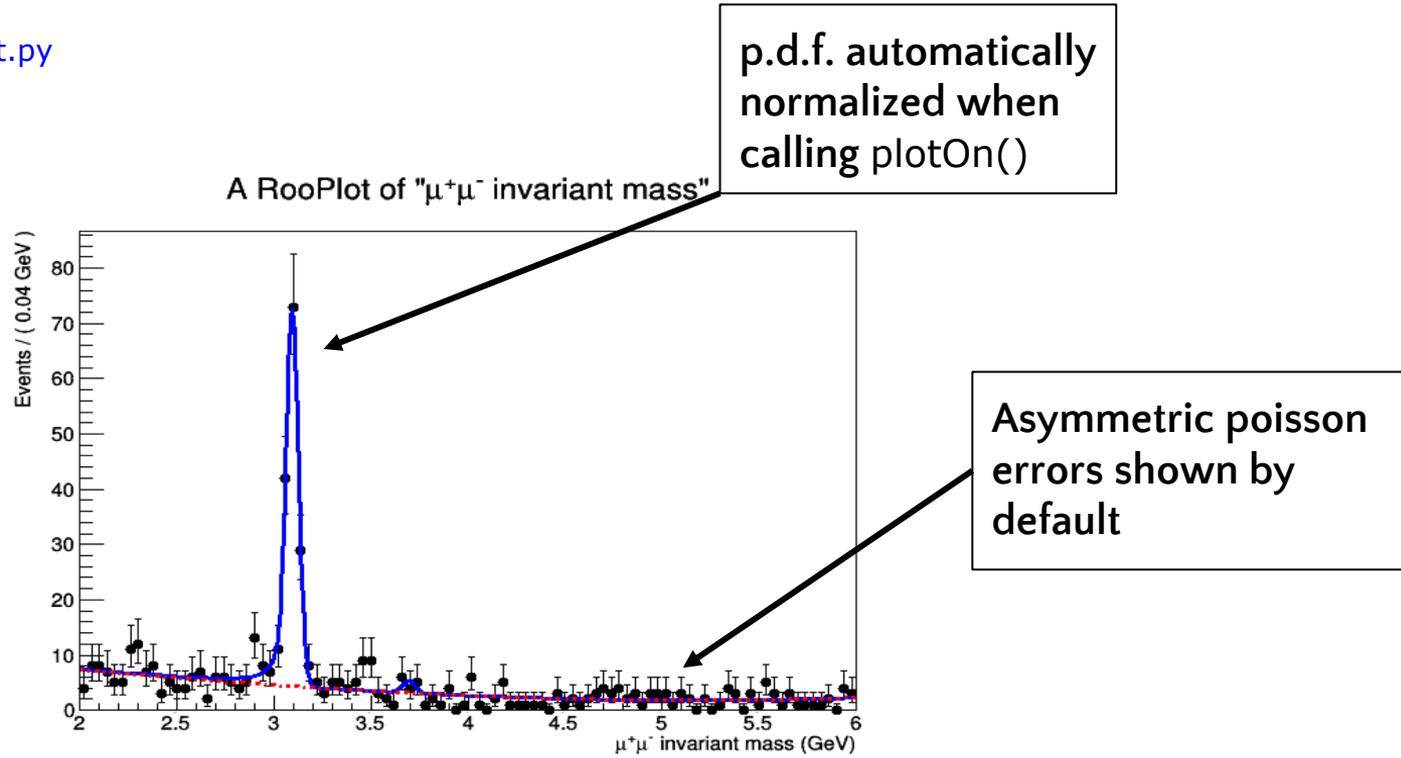
Save the data & fit result
into a RooWorkspace

Draw the data & fit result

Exercise 6: fitting with RooFit (\Rightarrow roofit.py)

Let's run it:

```
> python roofit.py
```



Exercise 6: fitting with RooFit (\Rightarrow Workspace_mumufit.root)

What is the measured cross section of $\Psi(2s) \rightarrow \mu\mu$?

```
> root -l -b Workspace_mumufit.root  
root[1] w = (RooWorkspace*) gDirectory->Get("ws")  
root[2] w->Print()  
root[3] w->var("cross_psi")->Print()
```

```
RooRealVar::cross_psi = 9.65042 +/- 7.94308 L(0 - 40) // [pb]
```

Exercise 7: profile likelihood scans

Suppose we want to look at the **profile log-likelihood** for one POI (say, J/ψ mass). This is an important sanity check of the fit (and remember Wilks' theorem!)

- An intensive task (one minimization per value of the POI)
- RooFit has a built-in method for doing it

$$PL(p) = \frac{L(p, \hat{q})}{L(\hat{p}, \hat{q})}$$

Exercise 7: profile likelihood (\Rightarrow profile.C)

```
{
  TFile* f = TFile::Open("Workspace_mumufit.root");
  RooWorkspace* w = (RooWorkspace*)f->Get("ws");
  w->Print();

  double xL = w->var("meanJpsi")->getVal() - 2.2* w->var("meanJpsi")->getError();
  double xU = w->var("meanJpsi")->getVal() + 2.2* w->var("meanJpsi")->getError();
  w->var("meanJpsi")->setRange(xL, xU);

  RooNLLVar nll("nll","nll",*(w->pdf("totPDF")),*(w->data("data"))) ;
  RooProfileLL pll("pll","pll", nll,*w->var("meanJpsi"));

  RooPlot* frame = w->var("meanJpsi")->frame(xL, xU) ;
  pll.plotOn(frame) ;
  frame->Draw();
}
```

Exercise 7: profile likelihood (\Rightarrow profile.C)

```
{
  TFile* f = TFile::Open("Workspace_mumufit.root");
  RooWorkspace* w = (RooWorkspace*)f->Get("ws");
  w->Print();

  double xL = w->var("meanJpsi")->getVal() - 2.2* w->var("meanJpsi")->getError();
  double xU = w->var("meanJpsi")->getVal() + 2.2* w->var("meanJpsi")->getError();
  w->var("meanJpsi")->setRange(xL, xU);

  RooNLLVar nll("nll","nll",*(w->pdf("totPDF")),*(w->data("data")));
  RooProfileLL pll("pll","pll", nll,*w->var("meanJpsi"));

  RooPlot* frame = w->var("meanJpsi")->frame(xL, xU) ;
  pll.plotOn(frame) ;
  frame->Draw();
}
```

Restrict scan to
reasonable interval
around the best-fit

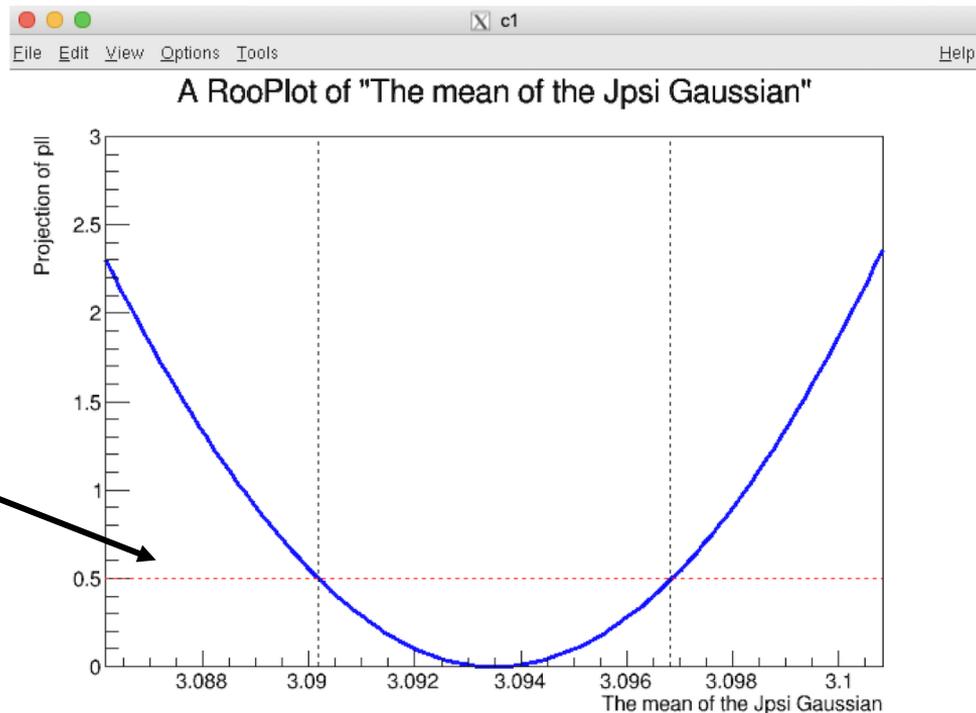
$NLL(\mu, \theta \mid \text{data})$.
(μ, θ are the best-fit results)

$NLL(\mu, \theta_\mu \mid \text{data}) - NLL(\mu, \theta \mid \text{data})$
(θ_μ is the best-fit result given μ)

Exercise 7: profile likelihood (\Rightarrow profile.C)

Let's run it:

```
> root -l profile.C
```



Add line segments (TLine) to visualize the 1σ CL intervals.

More into the future: RDataFrame (\Rightarrow test_RDF.C, read_RDF.C)

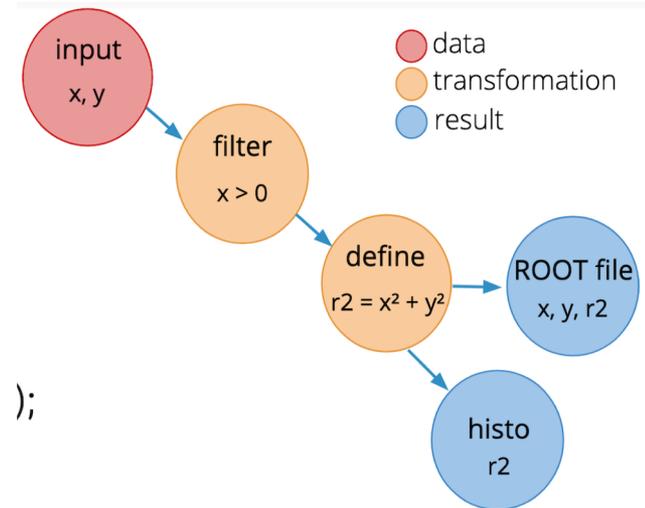
A tool for declarative analysis

- “Users say what, ROOT chooses how”
- Analysis as a computational graph of connected nodes: data \rightarrow operations \rightarrow results
- Computation of the graph **can be parallelized** in a transparent way

```
{  
ROOT::EnableImplicitMT();  
ROOT::RDataFrame df("tree", "tree_py.root", {"px", "py"});  
auto df2 = df.Filter("px > 0").Define("pT2", "px*px + py*py");  
auto rHist = df2.Histo1D("pT2");  
rHist->Draw();  
df2.Snapshot("newtree", "out.root");  
}
```

Let's run it:

```
> root -l test_RDF.C
```



Backup