

LEVERHULME TRUST \_\_\_\_\_

# Fast evaluation of Feynman integrals for MC generators

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In collaboration with W. Torres Bobadilla





Qgraf, Recola, FeynRules, FORM, FeynCalc, Tapir, ...

Amplitude

Master Integrals (MIs)

Evaluation of MIs

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- Fast integrator  $\rightarrow$  No mathematica package
- Precise, but no need for 50 significant figures!
- Ideally, fast enough not to use a grid



DiffExp [1] method: write Master Integrals in **differential form**, evolve it variable by variable from a boundary value to the desired final point with the **Frobenius method**. Avoid singularities with analytic continuation.

We could generate a grid of solutions with tools like DiffExp or SeaSyde [2], but dimensionality of the problem is large



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> What if we evolve the differential equations **numerically**?

C++ integrator







- 10 MIs, 5 orders of ε
- $O(\mu s)$  per phase-space point
- 7+ significant figures of precision

## Example 2.0





- 8 MIs, 5 orders of ε
- O(ms) per phase-space point
- 7+ significant figures of precision

#### The GVMD model

$$\begin{array}{cccc} & & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ &$$

$$F_{\pi}(q^2) = \sum_{v=1}^{3} a_v \frac{\Lambda_v}{\Lambda_v - q^2} = \sum_{v=1}^{3} a_v \left(1 + \frac{q^2}{\Lambda_v - q^2}\right)$$

## ISR NLO 28<sup>\*</sup> diagrams



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 $A_{TVP} \propto F_{\pi}(q_1^2) D_{\mu\nu}(q_1^2) F_{\pi}(q_2^2) D_{\mu\nu}(q_2^2)$ 

$$A_{TVP} \propto \sum_{w=1}^{3} \sum_{v=1}^{3} a_v \left( D_{\mu\nu}(q_1^2) + \frac{i\eta_{\mu\nu}}{\Lambda_v - q_1^2} \right) a_w \left( D_{\mu\nu}(q_2^2) + \frac{i\eta_{\mu\nu}}{\Lambda_w - q_2^2} \right)$$



 $e^{-}(q_1)$ 

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Still a 5 point integral at maximum, but we need to work with up to **9 kinematic variables**. We choose

$$\bar{x} = \{s_{14}, s_{15}, s_{23}, s_{24}, s_{35}, m_e^2, m_\pi^2, m_v^2, m_w^2\}$$

We have 16 possible combinations of  $m_v, m_w$  times 2 permutations of the external momenta



 $e^{-}(q_1)$ 

## The topologies

$$I^X_{a,b,c,d,e} = \int \frac{d^D k}{i\pi^{D/2}} \frac{1}{P_1^a P_2^b P_3^c P_4^d P_5^e}$$



_	MM	MN	NN
$P_1$	$m_w^2 - p^2$	$-p^2$	$-p^2$
$P_2$	$m_{\pi}^2 - (p - q_3)^2$	$m_{\pi}^2 - (p - q_3)^2$	$m_{\pi}^2 - (p - q_3)^2$
$P_3$	$m_e^2 - (p+q_2)^2$	$m_e^2 - (p+q_2)^2$	$m_e^2 - (p+q_2)^2$
$P_4$	$m_v^2 - (p + q_{124})^2$	$m_v^2 - (p + q_{124})^2$	$-(p+q_{124})^2$
$P_5$	$m_e^2 - (p + q_{24})^2$	$m_e^2 - (p + q_{24})^2$	$m_e^2 - (p + q_{24})^2$
	29 MIs	25 Mls	21 MIs

## **Obtaining the DE**

- Canonical MIs obtained by studying Leading & Landau singularities in different dimensions
- Use of **FiniteFlow** [3] to reconstruct the DEs with an ansatz based on the **alphabet**

$$d\bar{J} = \epsilon \sum_{i=1}^{n} \mathbf{A}_{i} dlog(\alpha_{i}) \bar{J}$$

• Letters of the alphabet predicted by combining **BaikovLetters** [4] and **Effortless** [5]

$$\alpha_{i} = \frac{P(\bar{x}) + Q(\bar{x})r_{k}}{P(\bar{x}) - Q(\bar{x})r_{k}} \qquad \qquad \alpha_{i} = \frac{P(\bar{x}) + Q(\bar{x})r_{k}r_{j}}{P(\bar{x}) - Q(\bar{x})r_{k}r_{j}}$$

[3] T. Peraro (2019) [4] X. Jiang (2024) [5] A. Matijašić, J. Miczajka (xxxx)

## Returning to the integrator...

- 1. Get partial DE w.r.t. each kinematic variable
- 2. Input expression for each MI and order of epsilon in terms of letters and other MIs
- 3. Input values for pre-canonical MIs obtained with AMFlow at a non-singular arbitrary point
- 4. Input singularities and branch cuts
- 5. Input expressions for derivatives of letters and square roots
- 6. Find optimal path between origin and desired final point for each kin. var.
- 7. Evolve the DE variable by variable in that path:
  - a. Multiply the AMFlow values by the canonical factors defined in terms of the current variable
  - b. Solve the coupled partial DE with controlled stepper from **Boost Odeint** library
  - c. Divide out the canonical factors from the solution
- 8. If desired, use the final result to go to a new final point

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10

Re[s<sub>35</sub>]





$$r_i = \sqrt{K_i^n(\bar{x})} \qquad \longrightarrow \qquad K^n(\bar{x}) = \prod_{j=1}^n (x - e_j) \qquad \longrightarrow \qquad \prod_{j=1}^n (x - e_j) - \lambda = 0$$

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We use the standard convention from mathematical software: branch cuts parallel to the negative real axis.









#### More analytic manipulation....

For the NN topology, more simplifications:

- No need for **21** MIs **x 3** O( $\epsilon$ ) **x 2** q(5)  $\leftrightarrow$  q(3)
- Use a rotation matrix R to evaluate only the relevant functions

$$\vec{W}(\vec{x};\epsilon) = R \, \vec{J}(\vec{x};\epsilon)$$

• By decomposing in terms of independent functions,

 $118\,\text{MIs}\,{\rightarrow}\,65\,\text{Ws}$ 

This can be applied to MN and MM, but less simplification is expected

#### **Check for the Ws**

• . . 0 -2000-4000-6000-8000 -10000This Work/Collier 10-11 10-11 10-13 10<sup>-13</sup> -12 -8 12 16 -160 4 8 -4**S**35

Comparison with Collier. Results of  $\boldsymbol{I}_{1,0,1,1,1}$  at finite order

\*Thanks to Daniel Gerardo Melo Porras



#### **Precision for MM**

Complex mass = x



**Precision for MM** 

#### Complex mass = x



Complex mass = x, y, z



**Precision for MM** 

Complex mass = x, y, z



Complex mass = x, y, z & 6 b.c





**Runtime for MM** 

Complex mass = x



Complex mass = x, y, z



**Runtime for MM** 

Complex mass = x, y, z



Complex mass = x, y, z & 6 b.c.



#### Next steps

- 1. Decompose amplitude in Form Factors
- 2. Implement in Phokhara, also GVMD amplitude (compare time with Collier)
- 3. Need for quad. prec. version to check error in higher orders of  $\varepsilon$
- 4. Generate small ~100 boundary values grid
- 5. Explore implicit methods for solving DEs, maybe exponential integrator?
- 6. Solving DEs numerically is a huge field, learn from them
- 7. NNLO  $\rightarrow$  See W. T. Bobadilla's talk

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## Thanks!